

# QNX BSP for phyCORE-i.MX35

#### **FULL Version**

by IBV - Echtzeit- und Embedded GmbH & Co. KG

Subject:	Release Notes
Version:	1.3, QNX 6.5
Date:	21.02.2014

# 1. Features

#### 1.1. Components of the BASE Version of the BSP

Component	Format	Features, Notes
Startup (BASE version)	Source	<ul> <li>Reads out MAC address from U-Boot environment in NOR flash</li> <li>Detects type of base board (PCM-970 or KSP-0155) automatically</li> </ul>
Serial	Source	<ul> <li>Supports i.MX35 UART1 and UART2</li> </ul>
FEC Network	Source	<ul> <li>Supports i.MX35 Fast Ethernet Controller (FEC)</li> <li>10/100 MBit speed</li> <li>Half / full duplex mode</li> <li>MAC address is used from U-Boot environment in NOR flash</li> <li>Additional library "devnp-shim.so" (part of QNX) is required for use of the driver with "io-pkt"</li> </ul>

### 1.2. Components of the FULL Version of the BSP

Component	Format	Features, Notes
Startup (FULL version)	Source	<ul> <li>Reads out MAC address from U-Boot environment in NOR flash</li> <li>Detects type of base board (PCM-970 or KSP-0155) automatically</li> </ul>
IPL	Source	<ul> <li>Small boot loader for fast booting the operating system from NOR flash.</li> <li>Boot menu for image selection</li> </ul>
USB	Binary	<ul> <li>Supports i.MX35 USB HOST Controller (EHCI) in full-speed mode</li> <li>Driver is shipped as binary without support</li> </ul>
I2C	Source	<ul> <li>Supports i.MX35 I2C1 and I2C3 in master mode and multi-master mode</li> </ul>
NAND	Source	<ul> <li>Supports NAND flash on phyCORE-i.MX35</li> </ul>
NOR	Source	<ul> <li>Supports NOR flash on phyCORE-i.MX35</li> </ul>
SD	Source	♦ Supports i.MX35 eSDHC controller
CAN	Source	<ul> <li>Supports i.MX35 CAN1 and CAN2 controller</li> <li>Supported baud rates: 500 k, 250 k, 125 k or manual adjustment of timing registers</li> <li>Provides QNX CAN interface (POSIX API): CAN IDs are represented in as device special files. Control of the driver is supported via devctl().</li> </ul>
RTC	Source	◆ Supports Real Time Clock on phyCORE-i.MX35



#### **1.3. Optional Driver Modules (not part of FULL Version of the BSP)**

GPIO		on request
Graphics	Source	<ul> <li>Supports i.MX35 graphic controller with OpenVG hardware acceleration for applications working with the GF interface</li> <li>QNX Photon applications use the frame buffer interface</li> </ul>
	Binary	<ul> <li>OpenVG Libraries are shipped as binary without support</li> </ul>

 $\Rightarrow$  Please contact IBV for more information

### 1.4. Further BSPs for PHYTEC Boards

A complete list of all available QNX Board Support Packages for embedded boards by PHYTEC Messtechnik GmbH is available at: http://www.ibv-augsburg.net/media/pdf/QNX\_BSP\_Overview\_PHYTEC.pdf

## 2. Target System

- Phytec CPU Module phyCORE-i.MX35 (PCB# 1315.4):
  - Freescale i.MX357 applications processor
  - ♦ 32 MB NOR-Flash
  - ◆ 1024 MB NAND-Flash
  - ♦ 128 MB DDR2-RAM
  - ♦ 532 MHz clock
- Phytec Mapper-Module PhyMAP-i.MX35 (PCB# 1318.2)
- Phytec Baseboard i.MX Carrier Board PCM-970 (PCB# 1280.4)

or:

- Phytec Baseboard KSP-0155-0 (PCB#PL2261.1)
- Bootloader U-Boot 2.0.0-rc10-ptx-PD10.1.2 (Feb 18 2011 11:28:15)
- Operating system QNX 6.5

# 3. Host Development System

- QNX Momentics 6.5
- Terminal emulation program (Qtalk, Momentics IDE Terminal, tip, HyperTerminal, etc.)
- RS-232 serial port or a USB-to-serial adapter, and a straight-through serial cable
- Ethernet link

### 4. Known Issues for This BSP

- The serial driver "devc-sermx1" doesn't support hardware flow control.
- Card insertion and removal detection isn't implemented in the "devb-mmcsd-imx35" driver. The SD card
  has to be inserted prior to starting the driver, and the card must not be removed while the driver is
  running.
- Because of a limitation of the QNX FFS3 library that's used by "devf-generic" to implement the flash file system and programming operations it isn't possible to erase the second, third and fourth block of the NOR flash (addresses 0xA0008000 to 0xA0020000) using QNX utilities.



### 5.1. Changes in Version 1.3

- I2C (bugfix): driver hung in multi-master operation when the CPU lost the arbitration
- CAN (enhanced): support of RTR, EID and LENGHT information
- CAN (enhanded): byte flipping for reading and writing of CAN messages changed
- Startup (bugfix): PATH set for qconn to support debugging
- FEC Network (bugfix): removed memory leak in case of lost RX packets
- FEC Network (bugfix): re-activate receiving after reading out from RX descriptor ring

### 5.2. Changes in Version 1.2.1

- IPL: changed minimum RAM-Refresh cycles from 8 to 16 (according to U-Boot 2.0.0-rc10-ptx-pcm043-1 (Jun 20 2011 - 14:47:46))
- IPL: changed NOR-Timing configuration

# 6. Sales / Technical Support

To get this BSP or to obtain technical support for the BSP, please contact:

### IBV - Echtzeit- und Embedded GmbH & Co. KG

Keltenstrasse 2 D-86343 Koenigsbrunn GERMANY Phone: +49 8231 9586-041 Fax: +49 8231 9586-049 Email: info@ibv-augsburg.net Web: http://www.ibv-augsburg.net ihy)